

ABSTRACT

A robot arm construction is provided with a robot arm for carrying a teat cup, which robot arm can be pivoted under the udder of the animal. The robot arm construction is provided with a first robot arm construction portion, a second robot arm construction portion, a first horizontal axis for enabling a pivoting movement of the first robot arm construction portion, and a second horizontal axis by means of which the second robot arm construction portion is pivotably connected to the first robot arm construction portion. The robot arm is connected to the second robot arm construction portion.

(Figure 1)